INFLUENCE OF A CME’S INITIAL PARAMETERS ON THE ARRIVAL OF THE ASSOCIATED INTEPLANETARY SHOCK AT EARTH AND THE SHOCK PROPAGATIONAL MODEL VERSION 3

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ABSTRACT

Predicting the arrival times of coronal mass ejections (CMEs) and their related waves at Earth is an important aspect of space weather forecasting. The Shock Propagation Model (SPM) and its updated version (SPM2), which use the initial parameters of solar flare-Type II burst events as input, have been developed to predict the shock arrival time. This paper continues to investigate the influence of solar disturbances and their associated CMEs on the corresponding interplanetary (IP) shock’s arrival at Earth. It has been found that IP shocks associated with wider CMEs have a greater probability of reaching the Earth, and the CME speed obtained from corona graph observations can be supplementary to the initial shock speed computed from Type II radio bursts when predicting the shock’s arrival time. Therefore, the third version of the model, i.e., SPM3, has been developed based on these findings. The new version combines the characteristics of solar flare-Type II events with the initial parameters of the accompanying CMEs to provide the prediction of the associated IP shock’s arrival at Earth. The prediction test for 498 events of Solar Cycle 23 reveals that the prediction success rate of SPM3 is 70%–71%, which is apparently higher than that of the previous SPM2 model (61%–63%). The transit time prediction error of SPM3 for the Earth-encountered shocks is within 9 hr (mean-absolute). Comparisons between SPM3 and other similar models also demonstrate that SPM3 has the highest success rate and best prediction performance.

Key words: shock waves – solar–terrestrial relations – Sun: coronal mass ejections (CMEs) – Sun: flares

1. INTRODUCTION

As one of the most violent forms of solar activity, coronal mass ejections (CMEs) can lead to non-recurrent geomagnetic storms when they collide with Earth’s magnetosphere if they contain a long and strong southward magnetic field component (Gosling et al. 1991; Dryer 1994; Green & Baker 2015). They are thought to be major sources of extreme space weather events. Fast CMEs usually drive an interplanetary (IP) shock ahead of them. IP shocks can accelerate particles in their propagation medium and produce large solar energetic particle events (Gopalswamy et al. 2003; Cliver & Ling 2009), compress the magnetosphere, and produce corresponding effects (Green & Baker 2015) when they reach the Earth’s orbit. Type II bursts are the evidence of these shock waves as they propagate in the solar corona and IP space. A review of the dynamic processes of CMEs in IP space is provided by Wang et al. (2013). Due to the important space weather effects of CMEs and their associated shocks, predicting their arrival times at Earth’s orbit with sufficient lead time has been a significant aspect of space weather prediction. Scientists have developed various kinds of models for the CME/shock arrival time prediction (e.g., Feng et al. 2009b, 2009a). Details of the principles of these models, as well as their current prediction status, can be found in the recent review paper of Zhao & Dryer (2014).

We have developed Shock Propagation Models, i.e., SPM (Feng & Zhao 2006) and SPM2 (Zhao & Feng 2014), to predict the shock arrival time at Earth. These models are based on an analytical solution to the propagation of blast waves in a moving medium. The inputs include the solar source location of the disturbance, the proxy piston driving time duration, the initial shock speed, and the background solar wind speed. The outputs determine whether or not the shock will hit Earth (SPM2) and the corresponding arrival time if it does (SPM2). Prediction results for 551 events of Solar Cycle 23 reveal that the prediction accuracies of SPM2 are similar to the Fearless Forecast models including STOA (Dryer & Smart 1984; Smart et al. 1984), ISPM (Smith & Dryer 1990, 1995), and HAFv.2 (Dryer et al. 2001, 2004; Fry et al. 2001, 2003, 2007; McKenna-Lawlor et al. 2002, 2006, 2012; Sun et al. 2002a, 2002b, 2003; Smith et al. 2005, 2009). The prediction success rate of SPM2 is ~ 60% for both the Earth-encountered and Earth-missed shocks. The prediction errors of the arrival time for Earth-encountered shocks are about 12 hr (rms error) and 10 hr (mean-absolute; MA error). SPM2 can now be freely accessed and used online (http://www.spaceweather.ac.cn/groupmodel.php?group=gamma).

However, it is difficult to further improve the prediction accuracy of SPM2. One of the most important reasons for this difficulty is that the model neglects characteristics of the associated CMEs in its inputs. Like the Fearless Forecast models, the shock’s initial speed adopted in SPM2 is computed from the frequency drift rate of metric Type II radio bursts. This speed is often different from the CME speed remote-sensing observed by coronagraphs on board spacecraft (e.g., SOHO/LASCO and STEREO/SECCHI). The other kinematic parameters of CMEs, such as angular width, are also not considered in the model. More and more evidence demonstrate that CMEs are closely related to their associated IP shocks. Therefore, the kinematic characteristics of CMEs should be considered in the arrival time prediction for the associated shocks. This is the goal of this paper.

2. SOLAR-IP SHOCK EVENTS AND THEIR ASSOCIATED CMEs

Zhao & Feng (2014) studied 551 solar disturbance events during the period 1997 February–2006 December. These
events were taken from the Fearless Forecast publications (Fry et al. 2003; McKenna-Lawlor et al. 2006; Smith et al. 2009), with the exception of some interacting events and questionable events, covering nearly the whole Solar Cycle 23. The following parameters for each event were used in Zhao & Feng (2014): the start time of the Type II burst, the source location of the associated flare, the coronal shock speed (computed from the Type II radio burst drift rate), the proxy piston driving time duration, the solar wind speed in the background, and the arrival time of the associated IP shock at L1 if it reached Earth. The corresponding IP shocks were observed at Earth for 202 events and were referred to as “without-shock” (abbreviated as “W-shock”) events; the other 349 events had no IP shocks observed at Earth and were called “without shock” (abbreviated as “W/O-shock”) events.

We add information from the CMEs associated with these 551 solar-IP shock events. For each event, we check the CME catalog observed by SOHO/LASCO (http://cdaw.gsfc.nasa.gov/CME_list/) to find its accompanying CME. The CME that satisfies the following requirements is believed to be associated with the solar-IP shock event: (1) the first appearance time of the CME in LASCO/C2 is within ±2 hr of the start time of the Type II burst; (2) the CME’s main propagation direction in LASCO’s observation is consistent with the source location of the solar-IP shock event; (3) if multiple CMEs satisfy (1) and (2), then we select the most eligible one. The Wind/WAVES Type II bursts and their associated CME (http://cdaw.gsfc.nasa.gov/CME_list/radio/waves_type2.html) catalog is also used for reference during our identification. For 202 “W-shock” events, there are 20 events during which LASCO/C2 had data gaps, and thus there is no evidence of associated CMEs. Therefore, we exclude these 20 “W-shock” events from this study. Similarly, 33 “W/O-shock” events which occurred when LASCO/C2 had data gaps are also excluded from this study. In this way, we obtain 498 solar-IP shock events as our event example, which includes 182 “W-shock” events and 316 “W/O-shock” events.

For the 182 “W-shock” events, 171 are associated with CMEs observed by SOHO/LASCO; the other 11 events are not associated with CMEs. Meanwhile, for 316 “W/O-shock” events, 269 are associated with CMEs observed by SOHO/LASCO; the other 47 events are not associated with CMEs. Therefore, the total sample of 498 events can be re-divided into four groups: Group I (GP I): 171 Type II-CME events with corresponding IP shocks at Earth; Group II (GP II): 11 Type II-non-CME events with their IP shocks at Earth; Group III (GP III): 269 Type II-CME events with no IP shock at Earth; and Group IV (GP IV): 47 Type II-non-CME events with no IP shock at Earth.

Figure 1 shows the number frequency distribution of 440 Type II-CME events (GP I + GP III) along the time difference (Δtstart) between the start of the Type II burst and the launch of the CME in LASCO/C2. Here, Δtstart > 0 indicates that the Type II start is earlier than the CME launch, while Δtstart < 0 indicates that the CME launch is earlier than the Type II start. This demonstrates that the Type II burst started before the CME launch (Δtstart > 0) for 404 of the total events. The normal distribution of the event number is centered at 0.46 hr, which is also the average of Δtstart for the total 440 events, as shown by the vertical arrow. The delay of the CME launch is, at least partly, due to the different detecting principles for Type IIIs and CMEs. The launch time of a CME adopted here is its first appearance in LASCO/C2. CMEs have propagated to a distance of about 2 to ~3 solar radii before they are detected by LASCO/C2. Therefore, this “launch time” is actually later than the triggering time of the eruption. On the other hand, the start time of a Type II burst, which corresponds to the formation time of a shock wave, is the time of energy release. This timing is near the triggering moment of a solar eruption, and should be earlier than the former. As a consequence, the start time of the Type II burst is adopted as the beginning of a solar event in the Fearless Forecast models.

3. THE SHOCK PROPAGATION MODELS

3.1. SPM

Feng & Zhao (2006) established the first version of SPM. This model was based on the combination of an analytic solution to the propagation of blast waves (Wei 1982; Wei & Dryer 1991) and the empirical estimation method of shock energy (Smith & Dryer 1990, 1995). The analytic solution of this non-similarity theory for blast waves started from basic equations of ideal fluid dynamics under a spherically symmetric hypothesis. As opposed to the classical similarity theory, this solution includes a moving, steady-state medium with variable density. “Steady-state” means that the background medium is in a state of dynamical equilibrium, and all of the parameters within it do not vary with time. The energy released from a point blast into the background medium is believed to be constant. After a series of complicated manipulations, the following equation is derived for the propagation speed (V_s) of the wave front along the radial distance R (in units of AU):

\[
\frac{dR}{dt} = \left[ -2\lambda_l + \sqrt{\left(2\lambda_l\right)^2 + \frac{E_0}{J_0R} + \frac{1}{2J_0}} \right] u_0. \tag{1}
\]

Here, \(u_0\) is the background solar wind speed, \(J_0 = \frac{3}{5}\), \(\lambda_l = -0.1808\); \(E_0\) represents the dimensionless form of the total energy \(E_s\) of the blast \(E_0 = \frac{E_s}{A u_0^2}\), and \(A = 300\, \text{kg m}^{-1}\).
The integral of Equation (1) provides the shock’s transit time \((TT)\) to \(R\):

\[
TT = \frac{J_0}{u_0} \left[ 4 \lambda_1 \left[ R + 2E_0 \right] + 2E_0 \ln(R + 2E_0) \right] - 8 \lambda_1 E_0 - 2E_0 \ln(R + 2E_0) \right] + 2 \sqrt{\frac{E_0 R}{J_0} + \left( 4 \lambda_1^2 + \frac{1}{2J_0} \right) R^2} \nonumber
\]

\[
\times \ln \left[ \frac{E_0 R}{J_0} + \left( 4 \lambda_1^2 + \frac{1}{2J_0} \right) R^2 + \frac{4 \lambda_1 E_0}{(R + 2E_0)} \right] + TT_0.
\] (2)

\(TT_0\) is computed by the requirement \(R = 0\) when \(TT = 0\). The shock’s total energy cannot be directly observed, requiring that a proxy be used. In the ISPM model, the shock’s total energy is believed to be proportional to its kinetic energy flux \(V_i^2\), longitudinal width \(\omega\), and the duration time \(\tau\) of the initial pulse:

\[
E_t = C \cdot V_i^2 \cdot \omega \cdot (\tau + D).
\] (3)

Here, \(C = 2.083 \times 10^{-20} \text{erg m}^{-3} \text{s}^{-2} \text{deg}^{-1}, D = 0.52 \text{hr}, \) and an average of angular width \(\omega_\lambda = 60^\circ\) is adopted. The combination of Equations (1)–(3) constitutes the SPM model. The input parameters of SPM include the initial shock speed \(V_{si}\) computed from the Type II radio burst drifting speed, the duration time \(\tau\) of the associated X-ray flare, and the background solar wind speed \(u_0\). The outputs of SPM provide the predicted \(TT\) of the shock to any radial distance \(R\) assuming that the shock will be able to reach \(R\).

### 3.2. SPM2

Although capable of predicting the shock’s arrival time, the SPM model cannot judge whether or not an IP shock will hit the Earth. The contribution of the shock’s propagation direction to its arrival time is also neglected in SPM. The application of the model to actual cases often leads to much faster predicted propagations of the shock than are observed. In addition, the initial shock speed computed from Type II radio bursts usually contains observational uncertainties due to the lack of spatial information. In order to overcome these drawbacks, Zhao and Feng (2014) put forward the second version of the model, i.e., SPM2. In SPM2, the following equation is adopted to compute the shock speed at a distance \(R\):

\[
V_i = \frac{dR}{dt} = \left[ -2 \lambda_1 + \sqrt{\left(2 \lambda_1\right)^2 + \frac{E_0}{J_0 R} + \frac{1}{2J_0}} \right] u_0 \times F_{AD} \times F_{PD}
\] (4)

with \(F_{AD} = 1.244 - 6.28 \times 10^{-3} u_0\), \(F_{PD} = 0.85 + 0.2 \cos \theta \cos \phi\), \(V_i^* = (0.3818 - 3.0 \times 10^{-4} V_i \sin \theta) V_{si} + V_{ai}, E_0 = C \cdot V_i^* \cdot (\tau + D)\). Here, \(F_{AD}\) and \(F_{PD}\) are the correction terms for acceleration/deceleration and the propagation direction, respectively. \(\theta\) denotes the source longitude and \(\phi\) denotes the source latitude of the shock. \(V_i^*\) is the initial speed of the shock adjusted from \(V_{si}\). The shock speed at the Earth’s location \((V_i(\text{EL}))\) can be computed from Equation (4), and then the Equivalent Shock Strength Index \((\text{ESSI})\) of the shock is

\[
\text{ESSI} = \frac{V_i(\text{EL}) - u_0}{V_i}.
\] (5)

Here, \(V_i\) is the fast-mode wave speed of the background solar wind at Earth, which is taken to be 100 km s\(^{-1}\). If \(\text{ESSI} \geq \text{ESSI}_{th} = 2.29\), then SPM2 predicts that the shock will reach the Earth and the corresponding \(TT\) at Earth is computed from

\[
TT = \frac{J_0}{u_0 \times F_{AD} \times F_{PD}} \left[ 4 \lambda_1 \left[ R + 2E_0 \right] + 2E_0 \ln(R + 2E_0) \right] - 8 \lambda_1 E_0 - 2E_0 \ln(R + 2E_0) \right] + 2 \sqrt{\frac{E_0 R}{J_0} + \left( 4 \lambda_1^2 + \frac{1}{2J_0} \right) R^2} \nonumber
\]

\[
\times \ln \left[ \frac{E_0 R}{J_0} + \left( 4 \lambda_1^2 + \frac{1}{2J_0} \right) R^2 + \frac{4 \lambda_1 E_0}{(R + 2E_0)} \right] + TT_0.
\] (6)

Otherwise, SPM2 predicts that the shock will miss Earth when \(\text{ESSI} < \text{ESSI}_{th} = 2.29\). The input parameters of SPM2 are the same as those of SPM with the addition of the shock’s source
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Table 1

<table>
<thead>
<tr>
<th>Mean Value</th>
<th>GP I (171)</th>
<th>GP II (111)</th>
<th>GP III (269)</th>
<th>GP IV (47)</th>
</tr>
</thead>
<tbody>
<tr>
<td>$V_i$ (km s$^{-1}$)</td>
<td>1231</td>
<td>943</td>
<td>980</td>
<td>953</td>
</tr>
<tr>
<td>$\gamma$ (hr)</td>
<td>1.81</td>
<td>0.81</td>
<td>1.16</td>
<td>0.92</td>
</tr>
<tr>
<td>$V_{CME}$ (km s$^{-1}$)</td>
<td>1108</td>
<td>...</td>
<td>672</td>
<td>...</td>
</tr>
<tr>
<td>$\alpha_{CME}$ (°)</td>
<td>262</td>
<td>...</td>
<td>142</td>
<td>...</td>
</tr>
<tr>
<td>$\tau_{AW}$ (m s$^{-2}$)</td>
<td>-8.72</td>
<td>...</td>
<td>-8.84</td>
<td>...</td>
</tr>
<tr>
<td>$\delta$ (sw) (km s$^{-1}$)</td>
<td>456</td>
<td>437</td>
<td>462</td>
<td>451</td>
</tr>
<tr>
<td>$\varphi$ (°)</td>
<td>43.3</td>
<td>25.8</td>
<td>54.9</td>
<td>37.8</td>
</tr>
</tbody>
</table>

Note. The event number of the four groups is given in parentheses. $V_i$ is the initial shock speed; $\tau$ is the proxy piston driving time duration; $V_{CME}$ is the linear speed of CMEs within LASCO’s FOV; $AW_{CME}$ is the sky-plane width of the CMEs, which is typically measured in the C2 FOV after the width becomes stable; $\alpha_{CME}$ is the acceleration of CMEs; $V_{SW}$ is the background solar wind speed; $\psi$ is the propagation angle of the shock relative to the Earth. All of the parameters are the averaged values of the corresponding group.

The Mean Value of the Initial Parameters for the Four Group Events

In order to better demonstrate statistically the influence of a CME on a shock’s arrival, Table 1 provides the mean values of the initial parameters for these four groups of events. In the following, $V_{ai}$ stands for the adjusted initial shock speed (i.e., $V_{ai}$ in Zhao & Feng 2014). $\tau$ is the proxy piston driving time duration. Here, the proxy piston driving time duration $\tau$ is defined as the interval between the two half-peak points of the GOES X-ray flux of the associated flare. It denotes the duration of the X-ray over half-peak flux. $V_{CME}$ is the CME speed obtained by fitting a straight line to the height-time measurements. Thus, it is an average speed within LASCO’s field of view (FOV). $AW_{CME}$ is the angular width of the CME projected on the sky-plane of SOHO. The angular width is typically measured in the FOV of LASCO/C2 after the width becomes stable. $\alpha_{CME}$ is the CME’s acceleration. $V_{SW}$ is the background solar wind speed. $\psi$ is the propagation direction angle of the shock, which represents the angular distance between the shock’s main propagation direction and the Sun–Earth line. All of the parameters listed in Table 1 are the averaged values of the corresponding group.

We qualitatively compare the parameters of the four groups as listed in Table 1. For GP I and GP II, all of their shocks reached Earth. GP I events are associated CMEs, but GP II events are not. The shock speeds of GP I are faster than those of GP II. The piston driving times of GP I are also longer than those of GP II. The background solar wind speeds of the two groups have no apparent differences. GP I shocks have larger direction angles than GP II shocks. It can be seen that solar disturbances associated with CMEs are stronger (faster, longer duration) than those with no CMEs. Meanwhile, the smaller direction angles of the latter group would help their shocks to reach Earth.

GP I and GP III are all associated with CMEs. The shocks of GP I arrived at Earth, but those of GP III did not. The speeds (both shock and CME) of GP I are faster than those of GP III. The durations of GP I are also longer than those of GP III. The mean value of the CMEs’ angular width for GP I (262°) is nearly twice that of GP III (142°). As for $\alpha_{CME}$ and $V_{SW}$, no significant differences are found between them. The direction angles of GP I are smaller than those of GP III. It follows that faster and wider disturbances have a higher probability of reaching Earth, but the larger propagation directions away from the Sun–Earth line would increase the disturbance’s probability of missing the Earth.

For GP II and GP IV, none of the shocks are associated with CMEs. The shocks of GP II arrived at Earth, but those of GP IV did not. The parameters of initial shock speed, time duration, and background solar wind speed for GP IV events are similar to those of GP II events. However, the direction angles of GP IV are larger than those of GP II. It seems that the greater propagation directions of GP IV shocks weaken their probability of reaching Earth.

For GP III and GP IV, no shocks arrived at Earth. GP III events are associated with CMEs, but GP IV events are not. The initial shock speeds for GP III are slightly faster than those of GP IV. The durations of GP III shocks are also longer than those of GP IV. The background solar wind speeds of the two groups are similar. The direction angles of GP III are obviously larger than those of GP IV. That is to say, these solar distances associated with CMEs are more violent. However, the direction of their propagation leads to their IP shocks missing the Earth.

4. INFLUENCE OF CME’S CHARACTERISTICS ON ARRIVAL OF THE ASSOCIATED SHOCK

4.1. With/Without CMEs

The combination of GP I and GP III provides 440 Type II burst events associated with CMEs, 171 of which have corresponding IP shocks reaching Earth; for the other 269 events, their IP shocks failed to reach Earth. The shock-arrival (at Earth) events account for 39% of the total events. Similarly, the combination of GP II and GP IV provides 58 Type II burst events with no associated CMEs, of which only 11 events have IP shocks arriving at Earth; the percentage of shock-arrival events is only 19%. We can see that the Earth-reaching probability for the CME-associated shocks is twice that of the non-CME-associated shocks.

4.2. CME Speed

Propagation speed is one of the most important factors determining the arrival times of solar transients. For each of the 440 Type II-CME events (GP I + GP III), we have two speeds, i.e., the initial shock speed $V_{ai}$ and the CME speed $V_{CME}$. These two speeds are obtained through different mechanisms, and have their own limitations and applications. $V_{CME}$ is measured by the coronagraph (LASCO) on the sky-plane perpendicular to the Sun–Earth line for SOHO, and therefore it does not represent the propagation speed of the CME in Earth’s direction. $V_{ai}$ is computed from the drifting speed of a Type II burst as the shock propagates from the high-density corona to the low-density IP medium. The shock speed derived in this way thus lacks directional information. $V_{CME}$ is often used in empirical models to predict the arrival times of CMEs and their related shocks. Meanwhile, $V_{ai}$ is widely used in physics-based models to predict the arrival of IP shocks. Figure 2 displays the variation of $V_{CME}$ plotted versus $V_{ai}$ for the 440 events. GP I events are denoted as asterisks and GP III events as pluses. The dashed line is the line to fit the data points for both GP I and GP III. The correlation coefficient (CC) between the two speeds is 0.55, which demonstrates a generally good correlation between the two speeds. The corresponding shock speed is usually large (small) for fast (slow) CMEs. The dotted line represents...
$V_{\text{si}} = V_{\text{CME}}$. It can be seen that $V_{\text{si}} > V_{\text{CME}}$ for 319 of the total 440 Type II-CMEs, and the average of $V_{\text{si}}/V_{\text{CME}}$ is 1.7. This means that the shock speed estimated from Type II radio bursts is usually larger than the CME speed obtained from coronagraph observations. This is consistent with the findings of Sun et al. (2002a). The reasons for this discrepancy could be as follows. On one hand, the $V_{\text{CME}}$ used here is the projected speed of CMEs on the sky-plane of SOHO, which is usually less than the radial speed of CMEs. On the other hand, $V_{\text{CME}}$ is actually the averaged speed within LASCO’s FOV. Fast CMEs will undergo decelerations during this stage. The averaged speed obtained in this way would be less than the initial speed (like $V_{\text{si}}$) in these cases.

We then investigate how well $V_{\text{si}}$ and $V_{\text{CME}}$ correlate with the shock’s TT at Earth. As no IP shock was observed at Earth for GP III events, only GP I events are analyzed. Figure 3 shows the variation of $TT$ plotted versus $V_{\text{si}}$ (Figure 3(a)), versus $V_{\text{CME}}$ (Figure 3(b)), and the CCs between them for 171 GP I events. The dashed line is the line to fit to data points. It follows that CC between $V_{\text{si}}$ and $TT$ is $-0.36$, and CC between $V_{\text{CME}}$ and $TT$ is $-0.35$. Their correlations are very similar. In other words, $V_{\text{si}}$ and $V_{\text{CME}}$ are equivalent as far as the prediction of $TT$ is concerned. We try to use their combination to construct a better input speed in the revised model. The following procedures are similar to the “parameter train” of the SPM2 model (Zhao & Feng 2014). First, we assume all of the other input parameters as well as the arrival times for these 171 GP I events, except for the input speed $V_{\text{si}}$. The SPM2 model is conversely used to compute the “expected” initial speed ($V_{\text{exp}}$) for each event. Then, we use the linear combination of $V_{\text{si}}$ and $V_{\text{CME}}$ to fit $V_{\text{exp}}$:

$$V_{\text{exp}} = c_0 + c_1 V_{\text{si}} + c_2 V_{\text{CME}}.$$  

For 171 GP I events, the least-squares fit to this two-variable linear regression equation can determine the coefficients $c_0$, $c_1$, and $c_2$:

$$
\begin{pmatrix}
  c_0 \\
  c_1 \\
  c_2
\end{pmatrix} = 
\begin{pmatrix}
  171 & \sum V_{\text{si}} & \sum V_{\text{CME}} \\
  \sum V_{\text{si}} & \sum V_{\text{si}}^2 & \sum V_{\text{si}} V_{\text{CME}} \\
  \sum V_{\text{CME}} & \sum V_{\text{si}} V_{\text{CME}} & \sum V_{\text{CME}}^2
\end{pmatrix}^{-1}
\begin{pmatrix}
  \sum V_{\text{exp}} \\
  \sum V_{\text{si}} V_{\text{exp}} \\
  \sum V_{\text{CME}} V_{\text{exp}}
\end{pmatrix}.
$$

In this manner we obtain $c_0 = 230.5$, $c_1 = 0.559$, and $c_2 = 0.274$. Therefore, the following equation will be adopted to compute the input speed $V_{\text{si}}$ in the new model:

$$V_{\text{si}} = 230.5 + 0.559 V_{\text{si}} + 0.274 V_{\text{CME}}.$$  

In addition, we also give the one-variable linear fit between $V_{\text{exp}}$ and $V_{\text{CME}}$:

$$V_{\text{si}} = 391.1 + 0.70 V_{\text{CME}}.$$  

which is derived in the same way as Equation (9) and can be used for CME-associated events without Type II bursts (not for this study).

### 4.3. CME Angular Width

Angular width is another important parameter for CMEs in coronagraph observations. Although it is only a two-dimensional (2D) angular width projected on the sky-plane of the SOHO spacecraft, $AW_{\text{CME}}$ can at least partially reflect how wide a CME is. CMEs are called partial halo CMEs if $120^\circ \leq AW_{\text{CME}} < 360^\circ$ and full halo CMEs if $AW_{\text{CME}} = 360^\circ$. We investigate the correlation between $AW_{\text{CME}}$ and $TT$ for 171 GP I events. We find that CC is only $-0.17$, indicating only a very weak correlation between $AW_{\text{CME}}$ and $TT$. Therefore, $AW_{\text{CME}}$ may make few contributions to the TTs of the associated shock.

On the other hand, the angular width of a CME is an important factor determining whether or not a CME encounters Earth (e.g., Shen et al. 2014). $AW_{\text{CME}}$ should contribute to the shock’s arrival as wider disturbances have a greater chance of reaching Earth. Figure 4 shows the number frequency distribution along $AW_{\text{CME}}$ for GP I (top) and GP III (bottom) events. The distributions are different for these two groups. For 171 GP I events, 97 events are associated with full-halo CMEs ($AW_{\text{CME}} = 360^\circ$), accounting for 56.7%; the average $AW_{\text{CME}}$ is $262^\circ$ for these 171 CMEs, as shown by the vertical dashed line. Meanwhile, for 269 GP III events, the number of full-halo CMEs is 42, accounting for only 15.6%; the peak of the event number distribution is located near $AW_{\text{CME}} = 60^\circ$ and the average $AW_{\text{CME}}$ is $142^\circ$ for these GP III events, as shown by the vertical dashed line. In other words, in a statistical sense, GP I CMEs are
significant wider than GP III CMEs. This proves the hypothesis that the width of a CME may potentially contribute to the associated shock’s arrival at Earth.

4.4. Judgements for Shock Arrival at Earth

A judgement index is needed in a prediction model to predict whether or not an IP shock will encounter Earth. In SPM2, ESSI is adopted as the judgement index. When $ESSI \geq ESSI_{tv1}$, the shock is predicted to reach Earth; otherwise, the shock is predicted to miss Earth. $ESSI_{tv}$ is the empirically prescribed threshold value of ESSI. We know from the above analysis that a CME’s angular width is also an important parameter influencing the associated shock’s arrival at Earth. Therefore, we can use the combination of ESSI and $AW_{CME}$ to predict the shock’s arrival for CME-associated events (GP I + GP III) in order to improve the prediction success rate. After a series of tests, the double standard, as follows, gives the best prediction. When $ESSI \geq ESSI_{tv1}$ and $AW_{CME} \geq AW_{tv}$, the shock is predicted to arrive at Earth; otherwise, the shock is predicted to miss the Earth. Here, $ESSI_{tv1} = 1.53$, $AW_{tv} = 121^\circ$. Figure 5 displays the scattered plot between ESSI and $AW_{CME}$ for 171 GP I events (solid circles) and 269 GP III events (hollow circles). It can be seen from Figure 5 that solar events with shock arrival at Earth generally have larger ESSI or $AW_{CME}$. However, there is still a large proportion of events with large ESSI or $AW_{CME}$ which are not followed by shock arrivals at Earth. Therefore, a single standard of ESSI or $AW_{CME}$ would usually inevitably lead to a certain amount of false alarms or misses. The double standard, on the other hand, would reduce the number of wrong predictions, as shown by the dashed–dotted lines. In Figure 5, the shocks in region I are predicted to reach Earth, and those in region II are predicted to miss Earth.

For 58 Type II-non CME events (GP II + GP IV), no CME angular width can be adopted in the judgement index. Therefore, ESSI becomes the only parameter used to predict a shock’s arrival at Earth. Figure 6 demonstrates the distribution of the prediction success rates for these 58 events along $ESSI_{tv2}$. The solid curve in this figure denotes the success rate of W-shock events, the dotted curve denotes that of W/O-shock events, and the dashed–dotted curve denotes that of all events. As opposed to SPM2, we do not select the intersection point of these curves as the final $ESSI_{tv2}$. Instead, we take $ESSI_{tv2} = 2.65$, shown as the vertical dashed line, in order to increase the prediction success rate of the total events. This $ESSI_{tv2}$ gives 3 “hit” predictions for 11 GP II events, 39 “correct null” (cn) predictions for 47 GP IV events, and the total prediction success rate for these 58 events is 72% (42/58).

5. SPM3 AND ITS PREDICTION RESULTS

5.1. SPM3

According to the above analysis, the new SPM3 model is defined as follows. For solar events associated with CMEs, both the initial shock speed $V_{si}$ and CME speed $V_{CME}$ are used to compute the initial speed of the disturbance $V_i$ based on Equation (9). This initial speed $V_i$, together with other input parameters, is used to compute the shock energy according to $E_0 = \frac{C}{\mu} \sqrt{\frac{W}{\delta_2}}$. Then, the disturbance’s propagation speed at Earth’s orbit and the corresponding ESSI are derived based on Equations (4) and (5). If $ESSI \geq ESSI_{tv1} = 1.53$ and
AW_{CME} \geq AW_0 = 121^\circ$, then the corresponding shock is predicted to be able to reach Earth, and its $7T$ is predicted based on Equation (6); otherwise, the shock is predicted not to reach Earth. For solar events associated with no CMEs, the shock speed $V_\text{sh}$ is used as the disturbance’s initial speed to compute $\text{ESSI}$ at Earth’s location. If $\text{ESSI} \geq \text{ESSI}_{b2} = 2.65$, then the shock is predicted to reach Earth and its transit time is obtained according to Equation (6); otherwise, the shock is predicted to miss Earth. The inputs to SPM3 are the same as those to SPM2, in addition to the speed and angular width of the associated CME in LASCO observations. The outputs of SPM3 include whether shocks will encounter Earth and their corresponding arrival times.

5.2. Prediction Results, Verification, and Statistics

Fundamental definitions of the prediction results are adopted in SPM2 and the Fearless Forecasts models to evaluate the efficiency of a prediction model. These definitions are as follows: “Hit” (h) when a shock is both predicted to arrive at Earth and is actually observed within $\pm 24$ hr of the predicted time; “Miss” (m) when a shock is observed but not predicted to arrive, or the predicted arrive time deviates $24$ hr away from the real one; “False alarm” (fa) when no shock is observed 1–5 days after the solar event but the model predicts it to arrive; and “No” (n) when a shock is neither observed 1–5 days after the solar event nor predicted to arrive. In this manner, the prediction of SPM3 for 498 sample events yields 122 hits, 90 false alarms, 60 misses, and 226 cns. In comparison, the prediction of SPM2 yields 112 hits, 124 false alarms, 70 misses, and 192 cns, and the prediction of HAFv.2 yields 139 hits, 186 false alarms, 43 misses, and 130 cns for these 498 events. Table 2 demonstrates the forecast $2 \times 2$ contingency table for the prediction results of SPM3, SPM2 compared with those of HAFv.2, STOA, and ISPM, respectively. This contingency table, usually adopted to evaluate meteorological models, has been transposed to list side by side the prediction results of different models (Schaefer 1990; Smith et al. 2000; Fry et al. 2001, 2003). Here, a, b, c, and d are the event numbers of h, fa, m, and cn, respectively. The total event number is given by $N = a+b+c+d$, which is 498 for the SPM3, SPM2, and HAFv.2 models. However, STOA was only available for 418 events, and ISPM was only available for 375 of the 498 total events in the Fearless Forecast predictions. In order to demonstrate the statistics more reasonably, this table lists the prediction results of SPM3, SPM2 compared with those of HAFv.2, STOA, and ISPM based on the same data samples, respectively. We know from the table that both the numbers of hits and cns for SPM3 are larger than those for SPM2. The total number of successful predictions $(a+d)$ is 348, 304, and 269 for SPM3, SPM2, and HAFv.2. The prediction of SPM3 gives the maximum number of successful predictions, which is 44 more than that of SPM2 and 79 more than that of HAFv.2. Similarly, the prediction for SPM3 provides 298 successes for 418 STOA events, 82 more than that for STOA (216) and 262 successes for 375 ISPM events, 42 more than that for ISPM (220). The successful prediction numbers of SPM2 lie between those of SPM3 and HAFv.2, STOA, and ISPM.

In order to further evaluate a model’s prediction efficiency, a series of statistical forecast skill scores are derived from the contingency table. These scores are as follows: (1) POD$_y = a/(a+c)$, probability of detection yes; (2) POD$_n = d/(b+d)$, probability of detection no; (3) FAR = $b/(a+b)$, false alarm ratio; (4) BIAS = $(a+b)/(a+c)$; (5) CSI = $a/(a+b+c+d)$, critical success index; (6) TSS = POD$_y + POD_n - 1$, true skill statistic; (7) HSS = $(a-d-C1)/(N-C1)$, Heidke skill score; and $C1 = C2 + (b+d)(c+d)/N, C2 = (a+c)(a+b)/N; (8) GSS = (a-C2)/(a+b+c+C2)$, Gilbert skill score; (9) SR = $(a+d)/N$, success rate. More details about these skill scores can be found in Schaefer (1990), Mozer & Briggs (2003), Smith et al. (2009), McKenna-Lawlor et al. (2012), and Zhao & Feng (2014). Each skill parameter reflects the prediction capability of a model on a certain aspect. For example, POD$_y$ denotes the ratio between the hit shocks and all of the Earth-encountered shocks. The value of 1 for POD$_y$ indicates that all of the Earth-encountered shocks are correctly predicted, and 1 is referred to as the “ideal value” of POD$_y$ for a “perfect” model. POD$_n$, on the other hand, denotes the ratio between cns and all of the Earth-missed events. Meanwhile, SR represents the prediction success rate for all of the events.

Table 3 shows a statistical comparison of these skill scores derived by SPM3, SPM2 with those derived by HAFv.2, STOA, and ISPM based on the same events. The ideal values of these skill scores for a perfect prediction are also shown in this table for reference. For all 498 events, SPM3 performs better than SPM2 for all of these nine skill scores. The prediction success rates of SPM3 for the Earth-encountered shocks (POD$_y$), the Earth-missed shocks (POD$_n$), and the total shocks (SR) are 67%, 72%, and 70%, which are 5, 11, and 9 percentage points higher than those of SPM2, respectively. This indicates a significant improvement in the forecast accuracy of SPM3 compared with the previous SPM2 model. Although HAFv.2 gives a greater success rate for the Earth-encountered events (POD$_y$) than SPM3 (76% versus 67%), it gives a much lower success rate for the Earth-missed events (POD$_n$: 41% versus 72%). The seven other skills of HAFv.2 are all worse than those of SPM3. In particular, the success rate for the total events (SR) of HAFv.2 is 16 percentage points

<table>
<thead>
<tr>
<th>Observation</th>
<th>SPM3 Prediction</th>
<th>SPM2 Prediction</th>
<th>HAFv.2 Prediction</th>
<th>SPM3 Prediction</th>
<th>SPM2 Prediction</th>
<th>STOA Prediction</th>
<th>SPM3 Prediction</th>
<th>SPM2 Prediction</th>
<th>ISPM Prediction</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td></td>
<td>a</td>
<td>c</td>
<td>122</td>
<td>60</td>
<td>112</td>
<td>70</td>
<td>139</td>
<td>43</td>
<td>99</td>
</tr>
<tr>
<td>No</td>
<td>b</td>
<td>d</td>
<td>90</td>
<td>226</td>
<td>124</td>
<td>192</td>
<td>186</td>
<td>130</td>
<td>68</td>
</tr>
<tr>
<td>Total</td>
<td>a+b</td>
<td>c+d</td>
<td>212</td>
<td>286</td>
<td>236</td>
<td>262</td>
<td>325</td>
<td>173</td>
<td>167</td>
</tr>
</tbody>
</table>

Note. This table is transposed from the format adopted by Smith et al. (2000), Fry et al. (2001, 2003), and McKenna-Lawlor et al. (2006) in order to facilitate the comparison of different models. Comparisons between SPM3, SPM2, and HAFv.2 are based on 498 events, between SPM3, SPM2, and STOA based on 418 events, and between SPM3, SPM2, and ISPM based on 375 events.
Statistical Comparison of the Values of Several Standard Meteorological Forecast Skill Scores Derived by SPM3, SPM2 With Those Derived by HAfv.2 Based on 498 Events, With Those of STOA Based on 418 Events, and With Those of ISPM Based on 375 Events

<table>
<thead>
<tr>
<th>Skill scores</th>
<th>Ideal value</th>
<th>SPM3</th>
<th>SPM2</th>
<th>HAfv.2</th>
<th>SPM3</th>
<th>SPM2</th>
<th>STOA</th>
<th>SPM3</th>
<th>SPM2</th>
<th>ISPM</th>
</tr>
</thead>
<tbody>
<tr>
<td>PODy</td>
<td>1</td>
<td>0.67</td>
<td>0.62</td>
<td>0.76</td>
<td>0.66</td>
<td>0.64</td>
<td>0.79</td>
<td>0.63</td>
<td>0.64</td>
<td>0.51</td>
</tr>
<tr>
<td>PODn</td>
<td>0</td>
<td>0.72</td>
<td>0.61</td>
<td>0.41</td>
<td>0.75</td>
<td>0.62</td>
<td>0.36</td>
<td>0.74</td>
<td>0.61</td>
<td>0.63</td>
</tr>
<tr>
<td>FAR</td>
<td>0</td>
<td>0.43</td>
<td>0.53</td>
<td>0.57</td>
<td>0.41</td>
<td>0.51</td>
<td>0.59</td>
<td>0.42</td>
<td>0.51</td>
<td>0.56</td>
</tr>
<tr>
<td>BIAS</td>
<td>1</td>
<td>1.17</td>
<td>1.30</td>
<td>1.79</td>
<td>1.11</td>
<td>1.32</td>
<td>1.91</td>
<td>1.08</td>
<td>1.31</td>
<td>1.15</td>
</tr>
<tr>
<td>CSI</td>
<td>1</td>
<td>0.45</td>
<td>0.37</td>
<td>0.38</td>
<td>0.45</td>
<td>0.38</td>
<td>0.37</td>
<td>0.43</td>
<td>0.38</td>
<td>0.31</td>
</tr>
<tr>
<td>TSS</td>
<td>1</td>
<td>0.39</td>
<td>0.22</td>
<td>0.18</td>
<td>0.40</td>
<td>0.26</td>
<td>0.15</td>
<td>0.37</td>
<td>0.26</td>
<td>0.14</td>
</tr>
<tr>
<td>HSS</td>
<td>1</td>
<td>0.37</td>
<td>0.21</td>
<td>0.15</td>
<td>0.39</td>
<td>0.24</td>
<td>0.13</td>
<td>0.36</td>
<td>0.24</td>
<td>0.14</td>
</tr>
<tr>
<td>GSS</td>
<td>1</td>
<td>0.23</td>
<td>0.12</td>
<td>0.08</td>
<td>0.24</td>
<td>0.14</td>
<td>0.07</td>
<td>0.22</td>
<td>0.14</td>
<td>0.07</td>
</tr>
<tr>
<td>SR</td>
<td>1</td>
<td>0.70</td>
<td>0.61</td>
<td>0.54</td>
<td>0.71</td>
<td>0.63</td>
<td>0.52</td>
<td>0.70</td>
<td>0.62</td>
<td>0.59</td>
</tr>
<tr>
<td>$\chi^2$</td>
<td>N</td>
<td>70.2</td>
<td>23.0</td>
<td>15.6</td>
<td>64.6</td>
<td>26.2</td>
<td>10.4</td>
<td>49.1</td>
<td>22.8</td>
<td>7.1</td>
</tr>
<tr>
<td>p-Value</td>
<td>0</td>
<td>0</td>
<td>1.6 $\times 10^{-6}$</td>
<td>7.7 $\times 10^{-5}$</td>
<td>8.9 $\times 10^{-16}$</td>
<td>3.1 $\times 10^{-7}$</td>
<td>1.3 $\times 10^{-3}$</td>
<td>2.5 $\times 10^{-12}$</td>
<td>1.8 $\times 10^{-6}$</td>
<td>7.7 $\times 10^{-3}$</td>
</tr>
</tbody>
</table>

**Note.** Here N is the total number of events that the model has predictions for, which is 498 for SPM3, SPM2, and HAfv.2, 418 for STOA, and 375 for ISPM. A $\chi^2$ test with a p-value is adopted to check the statistical significance of the forecasts. A larger $\chi^2$ value indicates a better dependence between observations and predictions, and a value of $p < 0.05$ indicates a high level of significance (better than the acceptable level when $0.05 < p < 0.2$) for the forecast.

To summarize, the prediction of SPM3 has the highest success rate and best performance compared with those of SPM2, HAfv.2, STOA, and ISPM. The success rate of SPM3 for all of the events is 79%, which is evidently higher than that of the previous SPM2 model (61%–63%), and even higher than those of HAfv.2, STOA, and ISPM (52%–59%).

### 5.3. The Prediction Error of TT

The prediction error of the shock’s TT at Earth, i.e., $\Delta T$, defined as the difference between the observed and predicted arrival times, is another parameter used to demonstrate the precision of the prediction models. The MA error and rms error are two commonly adopted measurements of $\Delta T$. Table 4 lists the prediction errors of these models based on the same data samples. The number of hit events in computing these errors is also shown. Among all 498 events, the MA $\Delta T$ of SPM3 is 9.01 hr for 122 hit shocks, which is less than both the 9.58 hr of the MA error for 112 hits (SPM2) and the 9.26 hr of MA error for 139 hits (HAfv.2); the rms error of SPM3 is 10.91 hr, which is also less than the 11.60 hr of rms error of SPM2 and the 11.34 hr of rms error of HAfv.2. Similar results are obtained for comparisons with STOA and ISPM. The MA error of SPM3 is 8.94 hr for 99 hits among 418 STOA events, which is less than both the 9.64 hr of the MA error of SPM2 and the 10.04 hr of the MA error of STOA; the rms error of SPM3 (10.76 hr) is the least among the three models. As for the 375 ISPM events, the MA and rms errors of SPM3 are 8.87 hr and 10.64 hr, respectively, which are less than the corresponding errors of SPM2 and ISPM. Briefly, the prediction errors of the shock TTs of SPM3 are within 9 hr (MA) and 11 hr (rms), which are the minimum among those of a group of models including SPM2, HAfv.2, STOA, and ISPM.

### 6. CONCLUSION AND DISCUSSION

Based on a set of 498 solar-IP shock events during 1997.02–2006.12, the influence of CMEs on associated shock arrivals at Earth are analyzed. It is found that the shocks associated with CMEs have a larger probability of reaching Earth than those not associated with CMEs. The angular width of the associated CME, although only a 2D projection on the sky-plane of the spacecraft, can be a useful index for judging...
whether the shock will hit Earth. The CME speed, obtained through remote-sensing observations of coronagraphs, are still valuable in predicting the shock arrival time. These results lead to the third version of SPM3. For the CME-associated events, the CME speed and the initial shock speed computed from Type II burst data are combined to compute the initial propagation speed of the disturbance in SPM3. A double Type II burst data are combined to compute the initial CME speed and the initial shock speed computed from remote-sensing observations of coronagraphs, are still valuable in predicting the shock arrival time. These results lead to the threshold value of ESSI. The prediction results of SPM3 for 498 sample events reveal that the success rate for all events is 70%–71%, which is significantly higher than that of SPM2 (61%–63%). The deviations of the predicted $TT$s of SPM3 are within 9 hr on the MA error and 11 hr on the rms error, which are less than those of SPM2. Comparisons between SPM3 and the Fearless Forecast models demonstrate the superiority of SPM3 as well.

Admittedly, although the prediction success rate of SPM3 is greatly improved compared with the previous SPM2 model, its improvements in the shock $TT$ prediction are limited. Many factors could potentially cause this. On one hand, the sample events used in this study are CMEs from Solar Cycle 23 when SOHO was the only spacecraft tracking their movements in the sky-plane. The CME speed derived in this way is the projected sky-plane. The CME speed derived in this way is the projected speed, which does not represent the propagation speed of the CME along the Sun–Earth direction. Large uncertainties in $V_{CME}$ restrict further improvements to the $TT$ prediction of the shock. Possible solutions to this restriction could include adopting the CME’s radial speed, which is derived from models (such as cone models) based on single spacecraft observations (Jang et al. 2014). Another solution involves estimating the initial geometry and three-dimensional (3D) speeds of CMEs based on observations from multiple spacecraft (STEREO, SOHO; Kilpua et al. 2012; Gopalswamy et al. 2013; Lee et al. 2013). On the other hand, the input parameters used in this study were obtained when the disturbances propagated near the Sun. Therefore, the lead time of SPM3’s prediction is very long, nearly the whole $TT$ of the disturbance from the Sun to Earth, as the model is analytic and thus requires no running time. Models based on heliospheric image data (STEREO HI and SMEI) can provide more accurate predictions for arrival times but with shorter lead times (Colaninno et al. 2013; Mishra & Srivastava 2013; Möstl et al. 2014). For example, Webb (2013) applied the Tapping–Howard model (Tapping & Howard 2009) to predict the arrival time at Earth of the 2011 February 15 CME event based on HI and/or SMEI observations, and the corresponding prediction accuracy could be within an hour. However, the prediction lead time was only several hours. Kilometric Type II radio burst emission can also be used to track shock dynamics in the inner heliosphere and provide shock arrive time predictions (Corona-Romero et al. 2013; Xie et al. 2013). Further prediction models considering these factors should be developed based on the events of Solar Cycle 24. This is the next goal of our research.

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